

CA-SpaceNet: Counterfactual Analysis for 6D Pose Estimation in Space

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Code: <https://github.com/Shunli-Wang/CA-SpaceNet>

Video: <https://www.youtube.com/watch?v=h-vzCdersVQ>



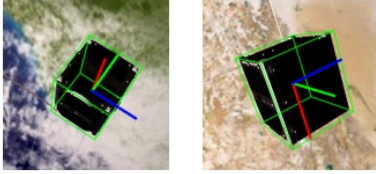
Outline

- 1. Background & Motivations
- 2. Proposed CA-SpaceNet
- 3. Experimental Results
- 4. Conclusion

Outline

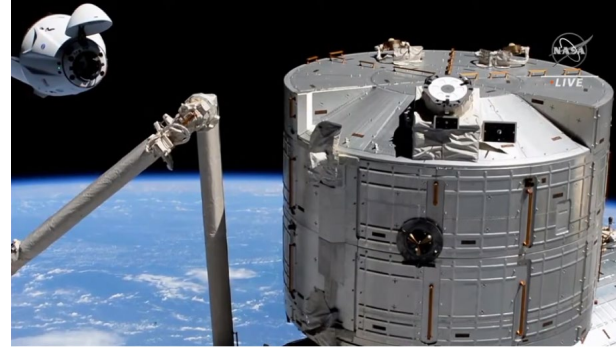
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1. Background & Motivations



Reliable and stable 6D
pose estimation algorithms

Basic technology



SpaceX Crew-2 Docking Mission

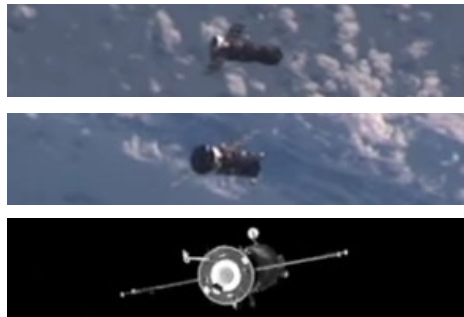


Preview of the ClearSpace-1

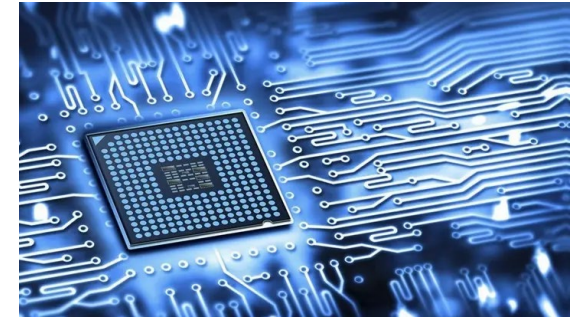
**Challenges
in the space scene:**



Harsh imaging conditions



Background interference



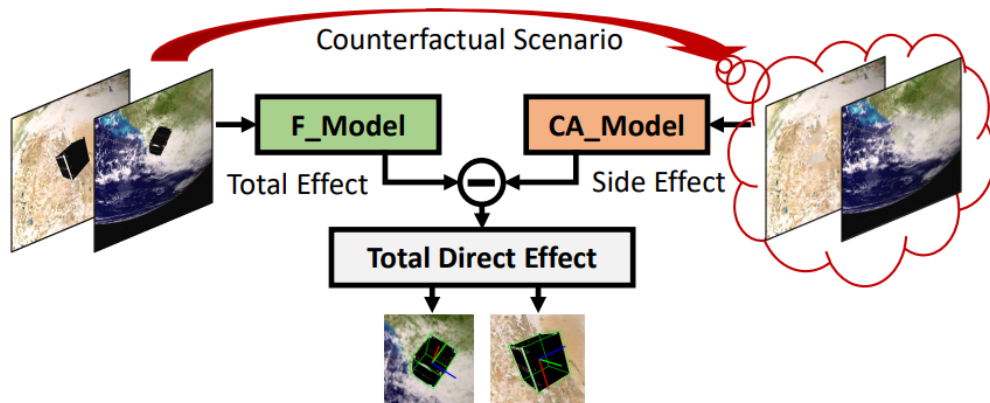
Limited power consumption

1. Background & Motivations

Complex Background Interference



How can we remove harmful features from the composite features?

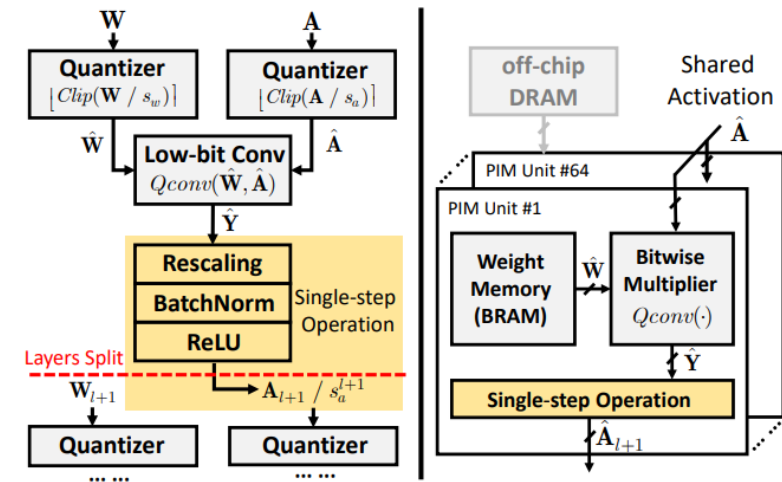


Main idea of the proposed CA-SpaceNet.

Limited Computing Resources & Power Consumption



How can we achieve efficient deployment of network models in low-power scenarios?

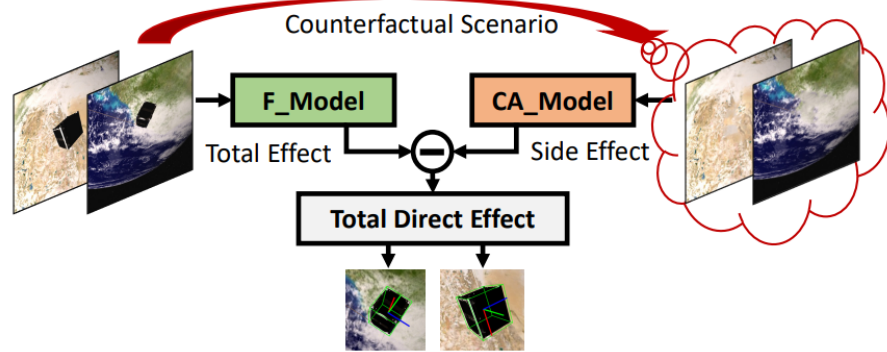


Quantization inference and the PIM accelerator architecture.

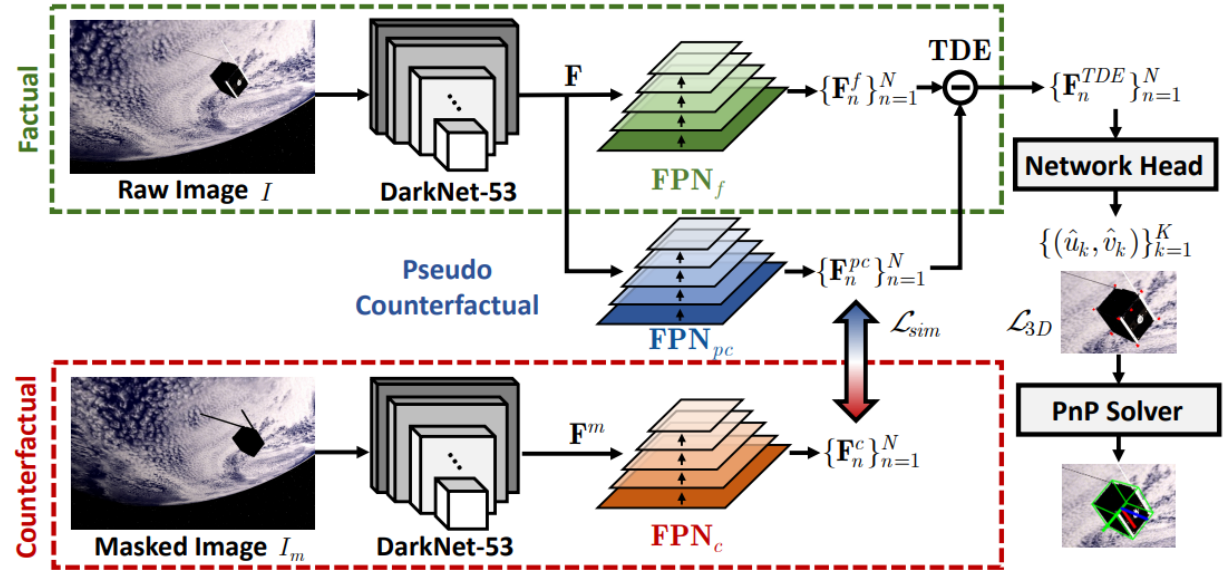
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2. Proposed CA-SpaceNet



Basic components of a two-stage 6D pose estimator.



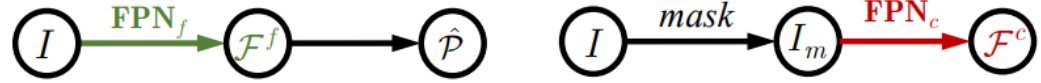
Actual network structure (CA-SpaceNet)

Factual path: Extract the feature of the whole image.

Counterfactual Path: Extract the feature of the background information.

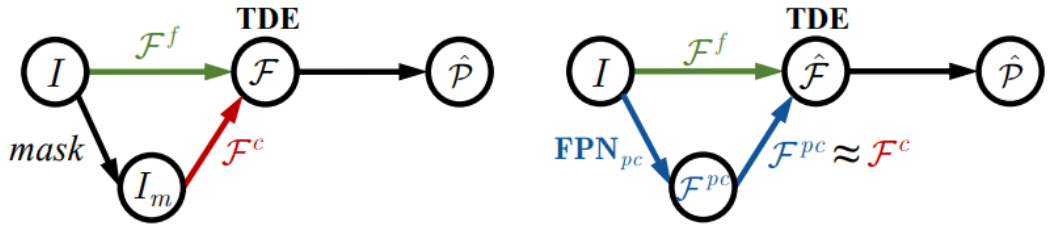
Pseudo Counterfactual Path: Mimic the output feature of the counterfactual path.

2. Proposed CA-SpaceNet



(a) Factual Path

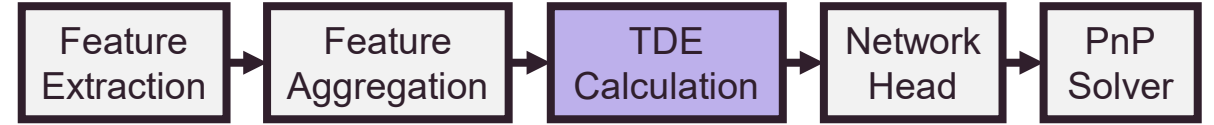
(b) Counterfactual Path



(c) Ideal Counterfactual Analysis

(d) Real Counterfactual Analysis

Simplified causal graphs of the CA-SpaceNet in four situations.



Five stages of the CA-SpaceNet.

Factual path: $\mathcal{F}^f = \mathbf{FPN}_f(\mathbf{F})$

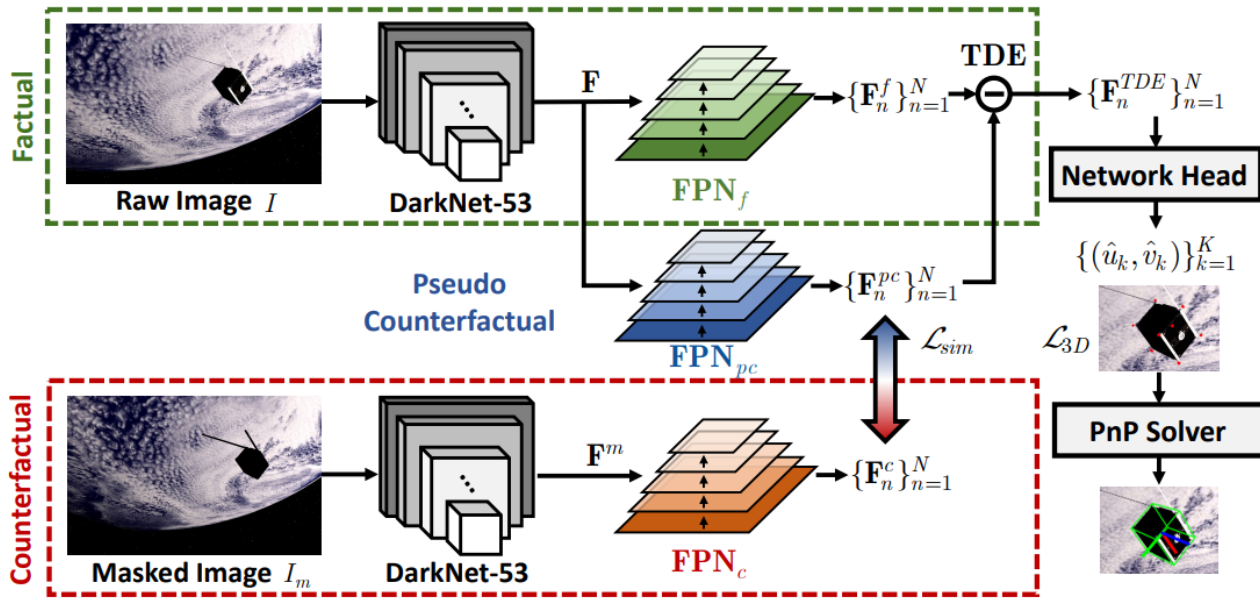
Counterfactual Path: $\mathcal{F}^c = \mathbf{FPN}_c(\mathbf{F}^m)$

Pseudo Counterfactual Path: $\mathcal{F}^{pc} = \mathbf{FPN}_{pc}(\mathbf{F})$

Total Direct Effect (TDE):
$$\begin{cases} \mathcal{F} = \mathcal{F}^f - \mathcal{F}^c \\ \hat{\mathcal{F}} = \mathcal{F}^f - \mathcal{F}^{pc} \end{cases}$$

\mathcal{L}_{sim}

2. Proposed CA-SpaceNet



Overview of the proposed CA-SpaceNet.

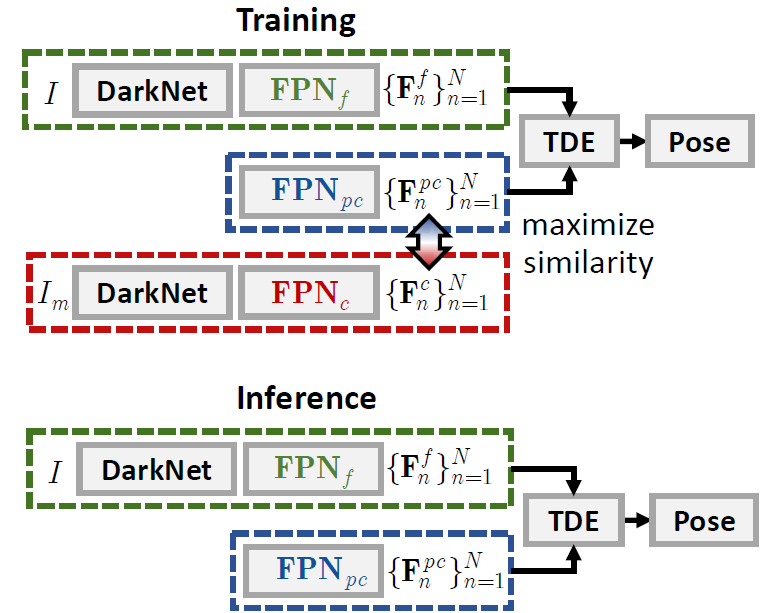


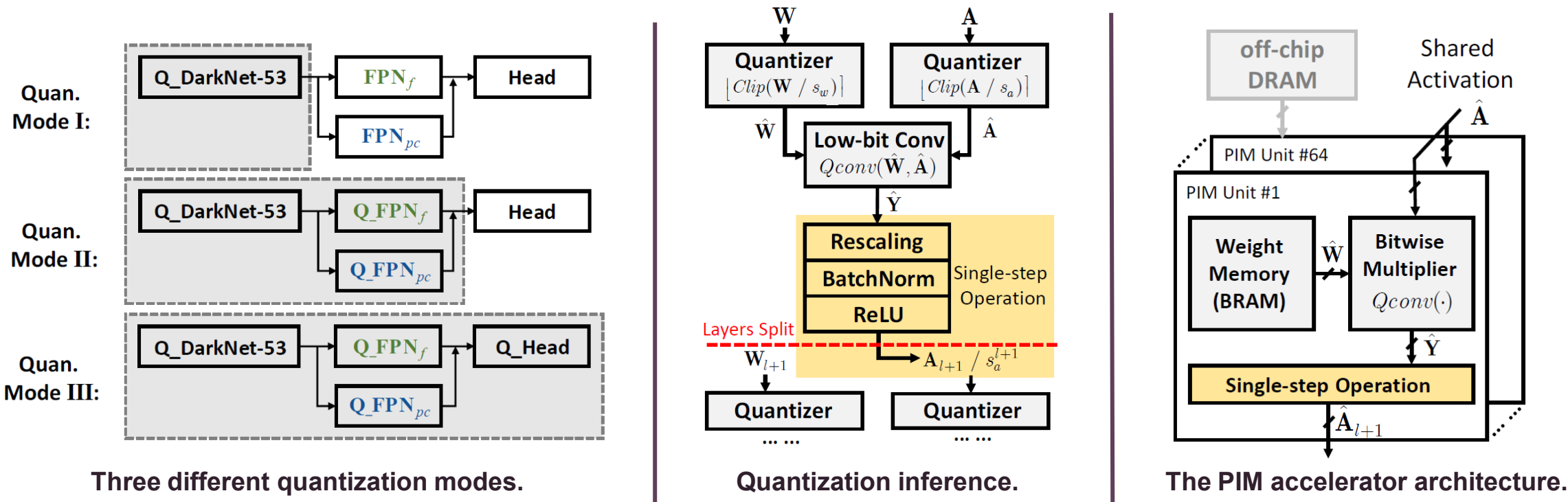
Diagram of training and inference phases.

- **Training:** FPN_{pc} will imitate FPN_c by maximizing the similarity between $\{F_n^{pc}\}_{n=1}^N$ and $\{F_n^c\}_{n=1}^N$.

$$\text{Total Loss: } \mathcal{L} = \lambda_{3D} \mathcal{L}_{3D} + \lambda_c \mathcal{L}_{cls} + \lambda_s \mathcal{L}_{sim}$$

- **Testing:** the whole counterfactual path will be removed during inference.

2. Proposed CA-SpaceNet



Quantized weights: $\hat{W} = [clip(W / s_w)]$

Quantized activations: $\hat{A} = [clip(A / s_a)]$

Low-bit-width convolution: $\hat{Y} = Qconv(\hat{W}, \hat{A})$

Dequantization: $Y = \hat{Y} * s_w * s_a$

Merge BN layer:
$$Y_{(i, :, :, :)}^{bn} = \frac{Y_{(i, :, :, :)} - \mu_i}{\sigma_i} \gamma_i + \beta_i$$

$$= \frac{\gamma_i}{\sigma_i} * s_w * s_a * \hat{Y}_{(i, :, :, :)} - \frac{\mu_i \gamma_i}{\sigma_i} + \beta_i$$

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3. Experimental Results

TABLE I

COMPARISON WITH STATE-OF-THE-ARTS ON SWISSCUBE.

Method	Near \uparrow	Medium \uparrow	Far \uparrow	All \uparrow
SegDriven [39]	41.1	22.9	7.1	21.8
SegDriven-Z [39]	52.6	45.4	29.4	43.2
DLR [5]	63.8	47.8	28.9	46.8
WDR [4]	65.2	48.7	31.9	47.9
WDR* [4]	92.37	84.16	61.27	78.78
CA-SpaceNet	91.01	86.32	61.72	79.39

TABLE III

COMPARISON WITH STATE-OF-THE-ARTS ON SPEED

Method	$e_q + e_t \downarrow$
SLAB Baseline [3]	0.0626
pedro-fairspace [42]	0.0571
WDR [4]	0.0180
WDR* [4]	0.0400
CA-SpaceNet	0.0385

TABLE II

COMPARISONS OF THE RE-TRAINING WDR* MODEL AND THE CA-SPACE NET.

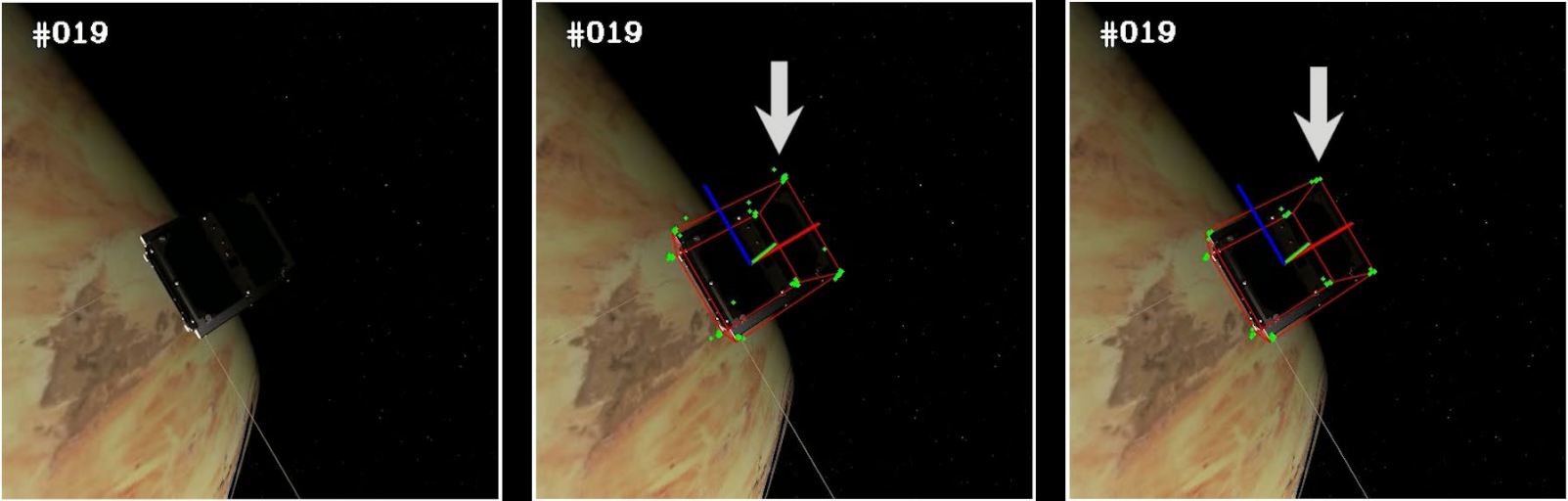
Method	Near \uparrow	Medium \uparrow	Far \uparrow	All \uparrow
WDR* [4]	92.37	84.16	61.27	78.78
WDR* [4] w. 30-Ep.	89.93 (-2.44)	82.09 (-2.07)	56.50 (-4.77)	75.76 (-3.02)
CA-SpaceNet	91.01 (-1.36)	86.32 (+2.16)	61.72 (+0.45)	79.39 (+0.61)

- The CA-SpaceNet can eliminate the interference of background through counterfactual analysis under the *Medium* and *Far* setting.
- The performance improvement is brought by the counterfactual analysis strategy rather than the additional 30 training epochs.

WDR*: note that the results of WDR on SPEED is obtained by the original paper without source code. We reproduced this model and reported our results as WDR*.

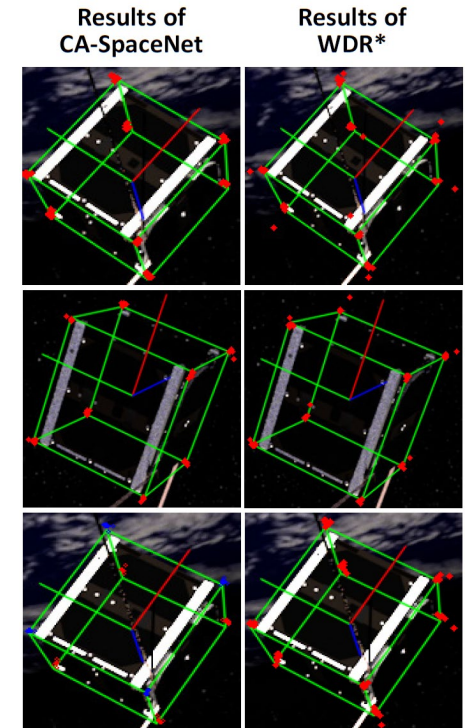
3. Experimental Results

testing_seq_000471
(Red boxes denote ground-truth pose. Green points denote prediction corners.)



Raw Video WDR* CA-SpaceNet

- ▶ In WDR*, the background interference makes the prediction points largely offset from GT corners.
- ▶ However, with the help of the causal inference strategy, the CA-SpaceNet successfully handles these complex situations.



The CA strategy is able to weaken the adverse impact of background interference to the final results.

3. Experimental Results

TABLE IV

RESULTS ON THREE DIFFERENT QUANTIZATION MODES OF 8-BIT AND 3-BIT CA-SPACENET ON SWISSCUBE

#Bits	Quan. Mode	ADI-0.1d ↑	OPs & FLOPs	Perc.(%)
8	I	76.21	36.91 GOPs + 33.79 GFLOPs	52.21
	II	75.04	44.51 GOPs + 26.19 GFLOPs	62.96
	III	74.65	70.47 GOPs + 0.23 GFLOPs	99.67
3	I	75.10	36.91 GOPs + 33.79 GFLOPs	52.21
	II	74.47	44.51 GOPs + 26.19 GFLOPs	62.96
	III	68.68	70.47 GOPs + 0.23 GFLOPs	99.67

TABLE V

SUMMARY OF PARAMETER STORAGE SIZE

Format	#Para.	Model Size	Stor. Saving (%) ↑
FP32	51.29 M	205.17 MB	0.00
8-bit	51.29 M	51.29 MB	75.00
3-bit	51.29 M	19.23 MB	90.63

TABLE VI

MEASURED LATENCY ON DIFFERENT HARDWARE

Device	Latency (ms) ↓
ARM v8.2 64-bit CPU (Nvidia Xavier)	26.16
Intel Core i7-8700K CPU	10.25
PIM Arch. on Ultra96v2 FPGA	5.99

- The quantization can save a large amount of GFLOPs without significantly reducing the performance.
- Quantization greatly reduce the size of the network which makes the model easier to be deployed on devices.
- Latency test results of the PIM chip shows the high efficiency of the quantization and our actual deployment.

3. Experimental Results

Latency Comparison

```
Terminal
agx@agx-jetson: ~/Desktop/CA-SpaceNet
agx@agx-jetson:~/Desktop/CA-SpaceNet$
agx@agx-jetson:~/Desktop/CA-SpaceNet$ cat /proc/cpuinfo | grep
name | cut -f2 -d: | uniq -c
      8 ARMv8 Processor rev 0 (v8l)
agx@agx-jetson:~/Desktop/CA-SpaceNet$ python3 test_conv.py
Avg. Lat. over 100 convolution operations: 30.67 ms
Avg. Lat. over 100 convolution operations: 26.70 ms
Avg. Lat. over 100 convolution operations: 28.73 ms
agx@agx-jetson:~/Desktop/CA-SpaceNet$ cat /proc/cpuinfo | grep
name | cut -f2 -d: | uniq -c
      8 ARMv8 Processor rev 0 (v8l)
agx@agx-jetson:~/Desktop/CA-SpaceNet$ python3 test_conv.py
```

ARM v8.2 64-bit CPU
(Nvidia Xavier)

```
(pytorch) D:\Code>wmic
wmic:root\cli>cpu get name
Intel(R) Core(TM) i7-8700K CPU @ 3.70GHz
wmic:root\cli>exit
(pytorch) D:\Code>python test_conv.py
```

Intel Core i7-8700K CPU

```
Jupyter CA-Space-Net-FPGA-Demo Last Checkpoint: 2020/09/02 (unsaved changes)
File Edit View Insert Cell Kernel Widgets Help
In [1]: import pytorch
import numpy as np
import time
from hw.Stalk_overlay import StalkOverlay
ol = StalkOverlay('/hw/ol')
In [2]: ol.download()
In [3]: # prepare xlink to store data in contiguous DOW memory
xlink = pytorch.xlink()
def xlink_create(d):
    d_xlink = xlink.cuda_array(shape=(len(d)), dtype=np.uint64)
    for i in range(len(d)):
        d_xlink[i] = d[i]
    return d_xlink
In [4]: def file_load(file_path):
    d = list()
    if file_path == '':
        return d
    with open(file_path, 'r') as f:
        lines = f.readlines()
        if not quiet:
            print('Loading file: %s' % file_path)
            for i in range(len(lines)):
                line = lines[i]
```

Processing-In-Memory Arch.
(3-bit PIM Accelerator on Ultra96v2 FPGA)

Latency ↓ 26.16 ms

10.25 ms

5.99 ms

Our deployment achieves **4.4x** speedup compared with ARM v8.2 CPU and **1.7x** speedup compared with Intel Core i7-8700K CPU.



Our real deployment of the **PIM architecture** on the Ultra96v2 FPGA achieves:

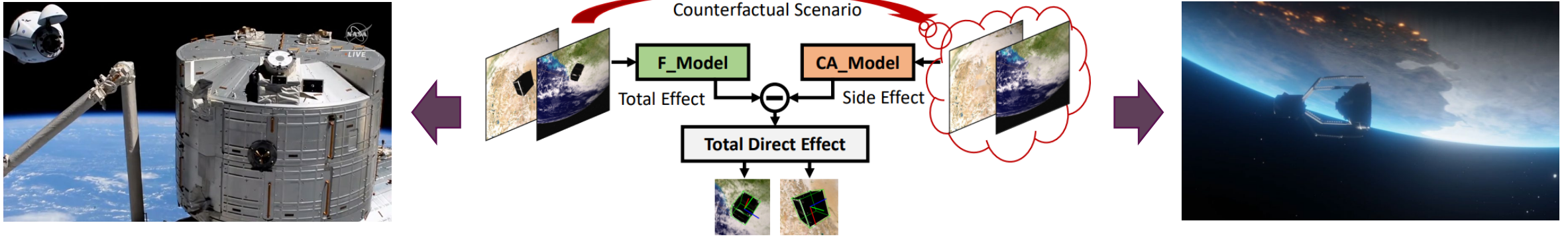
4.4x speedup than ARM v8.2 CPU,
&

1.7x speedup than Intel Core i7-8700K CPU.

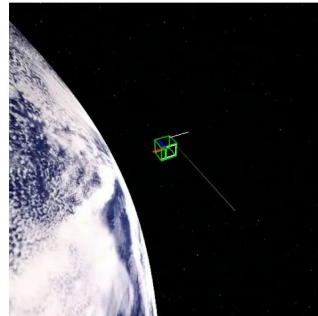
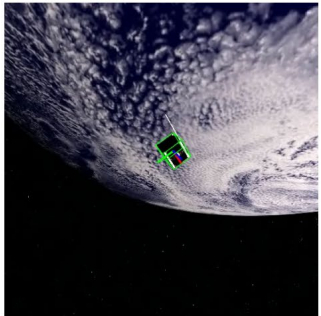
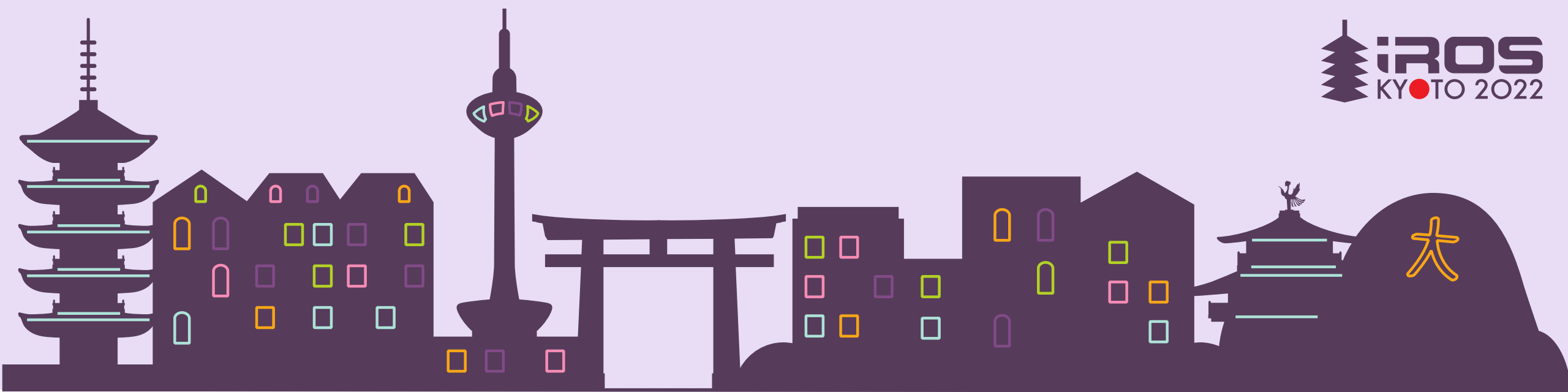
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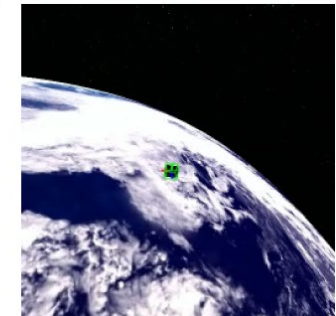
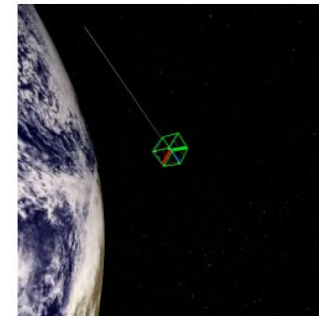
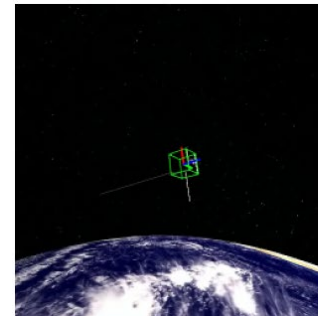
4. Conclusion



- We propose a framework named CA-SpaceNet, which is robust to the interference of complicated background information.
- Our approach outperforms state-of-the-arts on the challenging SwissCube dataset and achieves competitive results on the SPEED dataset.
- We quantize the CA-SpaceNet into a low-bit-width model and deploy a part of the quantized network into a Processing-In-Memory (PIM) chip on FPGA. Low latency proves the feasibility of our method.



Q&A



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